Lab1 GSI signoff sheet

1. Have your GSI check that your code is flashing the LED at 1Hz.
2. Have your GSI check that your LEDs are properly controlled by the pot. Also show your sketch that uses DDRx and PORTx to control the LEDs.
3. Have your GSI check your connections.

1. Demonstrate the working motor-control code to your GSI. Show what the motor outputs look like on an O-scope.

1. Show your GSI you can control the robot using the same motor controller you used in Part 4. You might want to slow down the motors so you have time to type the fairly long commands into the terminal.
2. Demonstrate your working motor (complete with an idle option) to your GSI.