

Approximate algorithms

EECS 477

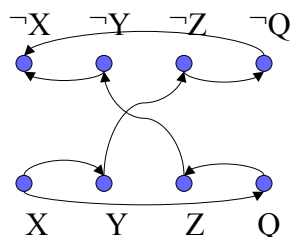
Lecture 23, 12/05/2002

SAT-2-CNF

■ Is in P

– Formula $(\neg X + Y)(\neg Z + \neg Y)(\neg Q + Z)(Q + \neg X)$

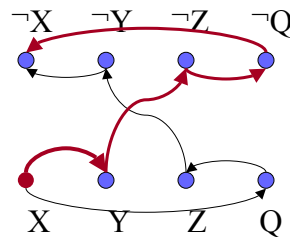
- Construct directed graph: two verts for each variable, edge from X to Y if there is a clause equiv to $(\neg X + Y) = \neg(\neg Y) + (\neg X)$



SAT-2-CNF

■ Claim

- If there are **paths** from some N to $\neg N$ **and** from $\neg N$ to N then the formula cannot be satisfied
- Otherwise it is satisfiable (example)



$X \Rightarrow Y$
 $Y \Rightarrow \neg Z$
 $\neg Z \Rightarrow \neg Q$
 $\neg Q \Rightarrow \neg X$
Hence
 $X \Rightarrow \neg X$
Hmm...

NP-completeness

- Decision problem X is NP-complete
 1. X is in NP
 2. $Y \leq^p X$ for **every** problem Y in NP
- X is polynomially harder than any other NP problem
- If we know that X is NP-complete and $X \leq^p Z$ then Z is NP-complete
- If we could only find one such X

Some NP-complete problems

- SAT
- 3SAT: clauses have three variables
- 3DM: 3D matching
- HAMD: hamiltonian circuit
- PARTITION: set A and $s:A \rightarrow \mathbb{Z}^+$
 - Partition A into two equally sized parts
- CLIQUE: clique of size J or more
- VERTEX COVER: of size K or less
- K-COL: graph colorability with K colors or less

NP-hard

- X is **NP-hard**
 - if there is an NP-complete problem Y that can be polynomially reduced to X
 - $Y \leq^p X$
 - Does not have to be a decision problem
 - Decision problem can be NP-hard but not in NP, for instance exact K-colorability
 - Any K-coloring is a certificate for K-COL but not for K-COLE(exact: can color with K but no less)

What about two colors?

- Determine whether a graph is two-colorable
 - A polynomial algorithm?

Metric TSP

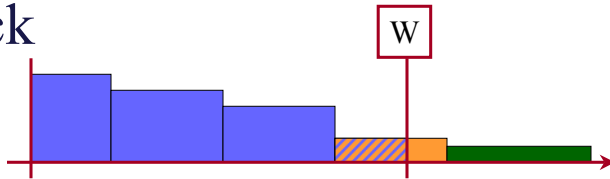
- Undirected graph (complete)
- Distance matrix satisfies
 - Triangle inequality
$$d(x,z) \leq d(x,y) + d(y,z)$$
 - $\text{length}(\text{Hamiltonian cycle}) \geq \text{length}(\text{Hamiltonian path}) \geq \text{length}(\text{MST})$
 - Construct an MST, tour around it will cost no more than $2 \cdot \text{length}(\text{MST})$
 - tour with shortcuts $\leq 2 \cdot \text{length}(\text{MST})$

Knapsack

■ Greedy

- Optimal when objects are breakable
- If not breakable:

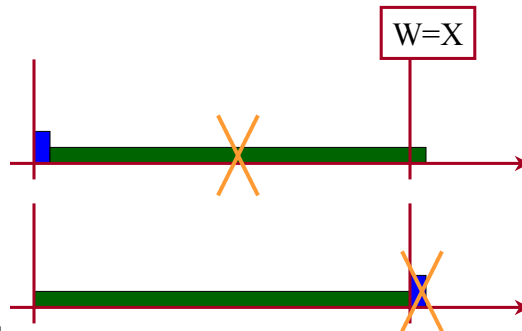
```
float greedy-knapsack(vector& w, vector& v, W){
    sort decreasing v[j]/w[j]
    weight = 0; value = 0;
    for(j=0; j<w.size(); ++j) {
        if(weight+w[j]<=W) { // add j-th object
            value += v[j]; weight += w[j];
        }
    }
    return value;
}
```



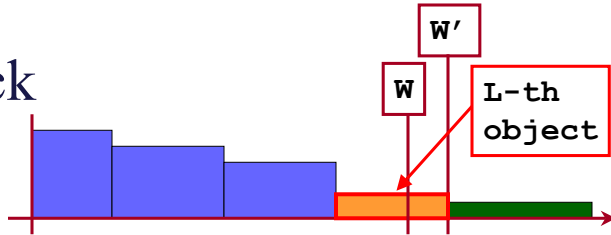
Knapsack

■ Bad example

- Ratio between optimal and greedy values
- $w[0]=1, v[0]=2, w[1]=X, v[1]=X$
- Greedy value is 2
- Optimal value is X
 - As X grows Optimal/Greedy goes to infinity



Knapsack



■ Fix it

```
float approx-knapsack(vector& w, vector& v, W){
    biggest_value = max(v);
    return max(biggest, greedy-knapsack(w,v,W);
}
```

- $Opt \leq Opt' = \text{sum}(v, j=0..L)$
- $Greedy = \text{sum}(v, j=0..L-1)$
- $Approx = \max(\text{biggest_value}, Greedy)$
- Claim: $Approx \geq Opt/2$

$$\text{Max}(a,b) \geq (a+b)/2$$

Approximations

- Maximization
- Different **guarantees**
 - Absolute
 - Absolute error is less than C
 - $Optimal - C \leq Abs-Approx \leq Optimal$
 - Relative
 - Relative error less than ϵ
 - $(1 - \epsilon)Optimal \leq Rel-Approx \leq Optimal$

MTSP

- $\text{MTSP} \leq^p \text{C-Abs-MTSP}$ for any $C > 0$
- Make new instance M'
 - multiplying the original distance matrix M by $K = \text{floor}(C) + 1$
- New approximate satisfies
 - $K * \text{Opt}(M) \leq \text{Aprx}(M') \leq \text{Opt}(M') + C = K * \text{Opt}(M) + C$
 - $\text{Opt}(M) \leq \text{Aprx}(M') / K \leq \text{Opt}(M) + C / K < \text{Opt}(M) + 1$
 - Everything is integer so $\text{Aprx}(M') / K = \text{Opt}(M)$

- EVALUATION FORMS!
- Tuesday: final exam review